# TEC2 Configuration file convert from TEC2000 (Model 500 Discontinued)

Using DCMlink<sup>™</sup>



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# Section 1: Document Purpose

This document is to show TEC user (1) how to export the configuration file from TEC2000 before perform the "TEC2 covert" which is changing electronics device inside TEC2000 unit into TEC2 electronics. (2) how to import TEC2000 configuration files into TEC2 electronics. There are two tools can be used to export the configuration from TEC2000 electronics actuator. First one is TEClink and second one is DCMlink<sup>™</sup>. Since TEClink is no longer support TEC2, DCMlink<sup>™</sup> becomes only available tools to access network to the configuration for configuration import process.Export TEC2000 configuration (Method: TEClink)

## 1.1 Export TEC2000 configuration (Method: TEClink)



- 1. Connect unit with RS485 Modbus on STC21/STC23 (RDM) or STC39 to STC44 with Modbus network.
- 2. TEClink export configuration from unit. (Using TEClink to export configuration file)
  - a) Set the comport and speed correct till the "Green" communication light shows at the button status bar which means the communication between TEClink and Unit has built up successfully.



3. Click Recv and wait 10 second till the button color comes back.



(Not avaliable-it's reading in process) (avaliable-it's finish reading process)

4. Click Save configuration file (.TEC) file at desire location



5. Save TEC2000 configuration file as unit serial number. (as example is 135614B01. TEC)



- 6. To make sure the TEC configuration export correctly, click "User" to read the current parameter from the unit.
- 7. Open the TEC configuration file from the location you saved.



8. If user does not see any column is blue after open the file, the configuration is export correctly.

| Configure TEC.  | 2000 Type 1   |         | - • •  |
|---|---|---------|--|
| Use   | er  | F       | actory   |
| Speed   | Analog  | Network |  |
| Control   | Inputs  | Outputs | Inhibit/ESD  |
| Control Mede<br>Deficie Ctri<br>Local Ctri<br>LED<br>Seat<br>Drive Sleeve | Two Wire<br>Maintain Knobs<br>Momentary Knobs<br>Open Red / Close O<br>Position<br>Close CW |         | 1 Enabled<br>2 Enabled<br>Enabled<br>ue Backseat<br>ue Retry |
| Close T<br>Open T   | orque 50% ÷   | 1       |  |

## 1.2 Export TEC2000 configuration (Method: DCMlink<sup>™</sup>)



Using DCMlink<sup>™</sup> to perform the configuration export, it requires the DCMlink<sup>™</sup> rev is greater than 1.2 and licensed. To perform export / import process, DCMlink<sup>™</sup> application requires to grand Emerson license.
 (Please consult Emerson Sales Team for more information).



- 2. Build up communication channel.
  - Click tool bar "DCMlink<sup>™</sup> Setup" a) B DCMlink™ Tag Network Actuator Setup Calibration Diagnostics Spec Sheet Tools DCMlink Setup He Preferences 石 👩 🌨 🦉 🕐 1 3 0 Security Groups Protocol « DCM Users 4 🚔 DCMlink Solo Version 2.0 0 Tag Group Names Modbus Tag Group Selections COM1 User ID : GJoshi : TESTER COM Security Group
  - b) Click "Preference"



c) High light the Modbus option and click "Add" button.

| Audit Log | Communication   | General   | Modbus  |   |
|-----------|---|---|---|---|
|           | Modbus<br>Modbus<br>COM1, 9600<br>COM3, 9600<br>HART<br>Fieldbus<br>Bluetooth | ion 2.0<br>), None, 1, 100ms D<br>), None, 1, 100ms D | elay Modbus Settings<br>Mode<br>COM Port<br>Baud Rate<br>Parity<br>Stop Bits<br>Timeout Delay | Image: Second state with the second state with the second state with the second state with the second state s |
| Add       | Remove  | Properties  | Save  | Cancel Help   |

d) In the Pop-up screen, Choose RDM Slave for TEC2000 and Choose COM port same as RS485 converter. The Baud Rate/ Parity/Stop Bits will be default as below number. Then Click the same button.

| Modbus Settings | · · · · · · |              |
|-----------------|-------------|--------------|
| Mode            | RDM Slave   | •            |
| COM Port        | COM2        | •            |
| Baud Rate       | 9600        | Ŧ            |
| Parity          | None        | Ŧ            |
| Stop Bits       | :[1         | Ŧ            |
| Timeout Delay   | : 100       |              |
|                 | (0 - 5000 m | illiseconds) |
| Encryption      |             |              |
| []              | Canad       | Uala         |

e) User should see the communication channel has built(RDM Slave) from DCMlink<sup>™</sup> as below. \*note: Only TEC2000 in DCMlink<sup>™</sup> will be required to use Slave mode to communicate unit.



- 3. Scan unit under communication channel
  - a) Right click on Comport and choose "Scan for New Device"

| *           | DCM  |  |   |
|-------------|--|--|---|
| ion 1.2     |  |  |   |
|             |  |  |   |
|             | Liser ID   |  |   |
|             | oser ib  |  |   |
|             | Security Group   |  |   |
| M Slave)    |  |  |   |
| Scan For Ne | w Devices 🧲  | /e   |   |
| Refresh     |  |  |   |
| Stop RDM S  | lave   |  |   |
| Live Commu  | nication Viewer  | nation   |   |
|             | Mac  | hine Name  |   |
|             | Baud   | d Rate   |   |
|             | Parit  | y  |   |
|             | Stop   | Bits   |   |
|             | sion 1.2<br>Scan For Ne<br>Refresh<br>Stop RDM S<br>Live Commu | sion 1.2 User ID Security Group      Scan For New Devices Refresh Stop RDM Slave Live Communication Viewer      Mac Bauc Pariti Stop | sion 1.2<br>User ID :<br>Security Group :<br>Scan For New Devices re<br>Refresh<br>Stop RDM Slave<br>Live Communication Viewer nation<br>Machine Name<br>Baud Rate<br>Parity<br>Stop Bits |

- b) Enter the unit choose to 0 and click start to scan network.
- The red color of 0 which means the unit is not available at the network.
- The blue color of 0 which means the unit is available at the network.

| Modbus Network Scan  |                                       |
|--|---------------------------------------|
| Scan -<br>Polling Range 0<br>Note: Polling range for RDM protocol is 0 | Start<br>Stop                         |
| Address Status/Selection   | Key<br>TEC2000<br>Unknown<br>No Reply |
|  | Help                                  |
|  | Close                                 |

| Modbus Network Scan                       |         |
|---|---------|
| Scan                                      |         |
| Polling Range 0                           | Start   |
| Note: Polling range for RDM protocol is 0 | Stop    |
| Address Status/Selection                  | Key     |
| 0   | TEC2000 |
|   | Unknown |
|   | No Penh |
|   | но керу |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   |         |
|   | Help    |
|   | Close   |

c) Once unit found in the network and close the pop-up screen of MODBUS, user should see the unit serial number shows under the "COMPORT (RDM Slave)"



- 4. Enter unit setup menu to export the configuration file.
  - a) Right click on the unit S/N and choose the "Detailed Setup"



b) Processing of communication to TEC2000 unit will show below prompt



c) Location the "Export configuration" and click to save the configuration

|              |                      |             |              |          |         |                              |                            |        | Read      |              |
|--------------|----------------------|-------------|--------------|----------|---------|------------------------------|----------------------------|--------|-----------|--------------|
| Dataset      |                      |             |              |          |         |                              |                            |        |           |              |
| New          |                      |             |              |          |         |                              |                            | * Send |           | Sync Dataset |
| Control      | Discrete Inputs Rela | ys Analog   | ESD/Inhibits | Speed    | Network | c No                         | tes                        |        |           |              |
| Paramete     | r                    | Actuator    |              |          |         |                              | Dataset                    |        |           |              |
| Control Mo   | de                   | Analog      |              |          | +       | >                            | Analog 🔹                   |        |           | <u> </u>     |
| Remote Cor   | ntrol Signal         | Maintained  |              |          | -       | >                            | Maintained •               |        |           |              |
| Local Contro | ol Signal            | Momentary   |              |          | -       | •                            | Momentary •                |        |           |              |
| Seating      |                      | Position    |              |          | +       | >                            | Position -                 |        |           | E            |
| Backseat     |                      | Position    |              |          | +       | >                            | Position -                 |        |           |              |
| LED Color    |                      | Open Red/Cl | ose Green    |          | +       | >                            | Open Red/Close Green 🔹     |        |           |              |
| Close Torqu  | e Limit              | 50          |              | %        | +       | •                            | 50 % 🗘                     |        |           |              |
| Open Torqu   | e Limit              | 50          |              | %        | -       | •                            | 50 % 🗘                     |        |           |              |
| Enable RDN   | 11                   | No          |              |          | -       | >                            | No •                       |        |           |              |
| Enable RDN   | 12                   | No          |              |          | -       | >                            | No •                       |        |           |              |
| Torque Retr  | У                    | No          |              |          | -       | >                            | No                         |        |           |              |
| Enable Low   | Battery Alarm        | No          |              |          | -       | >                            | No                         |        |           |              |
| Enable Setp  | oint Tracking        | No          |              |          | -       | >                            | No                         |        |           |              |
| Ignore 3% T  | orque Pullout        | No          |              |          | (       | $\left  \rightarrow \right $ | No                         |        |           | *            |
| Save Data    | set Reset Dataset    | Delete Da   | taset Copy F | rom Tag  | Load (  | Configu                      | ation Export Configuration |        | Close Tag | Help         |
|              |                      |             |              |          |         |                              |                            |        |           |              |
|              | d)                   | Save        | e file v     | vith     | uni     | ts                           | erial number.              |        |           |              |
|              | -<br>File name       | E TEC20     | 00_135614    | B01      | .cfg    |                              |                            |        |           | •            |
|              | Save as type         | : Config    | documen      | t (*.cfg | I)      | K                            |                            |        |           | -            |
|              |                      |             |              |          |         |                              |                            |        |           |              |

## **NOTE:**

Hide Folders

During the export process, the format of configuration file generate from TEClink is \*.TEC and the format of configuration file generate from DCMlink<sup>™</sup> is \*.cfg. the contents of configuration file are same either it's generated from TEClink or DCMlink<sup>™</sup>.

Save Cancel

# 1.3 Import configuration to TEC2 unit (Method: DCMlink<sup>™</sup>)

1. Set the comport with baud rate 115200 (Modbus Master)-if go through STC36 / STC38. Set the comport with baud rate 9600 (Modbus-bus/Modbus repeater)-if go through STC 39 to STC44, Modbus Network channel A and B.

| Perferences                                    | x    |
|--|------|
| Communication General                          |      |
|  |      |
| DCMlink Solo Version 1.2                       |      |
| Modbus   |      |
| 🜮 COM1, 115200, None, 1, 100ms Delay           |      |
| COM37, 115200, None, 1, 100ms Delay            |      |
| COM31, 115200, None, 1, 100ms Delay            |      |
| 🏠 COM2, 9600, None, 1, 100ms Delay (RDM Slave) |      |
| 🚯 Bluetooth                                    |      |
| HART   |      |
| Fieldbus                                       |      |
|  |      |
|  |      |
| Add Remove Properties                          |      |
| OK Cancel H                                    | lelp |

- 2. Scan the unit through comport with unit address 1.
  - a) The dark green color as below is recongized as TEC2 unit.
  - b) The Pink color as below is recongized as MODEL500 unit. (Default) (Model 500 Discontinued)

| Mod      | bus Ne   | twork S   | Scan   |         |          |         |     |     |      |      |      |     | ×          |
|----------|----------|-----------|--------|---------|----------|---------|-----|-----|------|------|------|-----|------------|
| Scan -   |          |           |        |         |          |         |     |     |      |      |      |     | ]          |
| Polling  | Range    |           | 1      |         |          |         |     |     |      |      |      |     | Start      |
| Note: P  | olling r | range fo  | or Mod | bus pro | tocol is | 1 - 253 | 5   |     |      |      |      |     | Stop       |
| - Addros |          | vs /Solos | tion   |         |          |         |     |     |      |      |      |     | Kay        |
| Addres   | SJatu    | IS/ JEIEC |        | 0.4     |          | 4.24    |     |     | 4.04 | 0.04 | 0.04 | 244 | ( Key      |
| 1        | 21       | 41        | 61     | 81      | 101      | 121     | 141 | 161 | 181  | 201  | 221  | 241 | M2CP       |
| 2        | 22       | 42        | 62     | 82      | 102      | 122     | 142 | 162 | 182  | 202  | 222  | 242 | MPA        |
| 3        | 23       | 43        | 63     | 83      | 103      | 123     | 143 | 163 | 183  | 203  | 223  | 243 | 1100001100 |
| 4        | 24       | 44        | 64     | 84      | 104      | 124     | 144 | 164 | 184  | 204  | 224  | 244 | HQDCM33    |
| 5        | 25       | 45        | 65     | 85      | 105      | 125     | 145 | 165 | 185  | 205  | 225  | 245 | HQDCM32    |
| 6        | 26       | 46        | 66     | 86      | 106      | 126     | 146 | 166 | 186  | 206  | 226  | 246 | TECOOO     |
| 7        | 27       | 47        | 67     | 87      | 107      | 127     | 147 | 167 | 187  | 207  | 227  | 247 | TEC2000    |
| 8        | 28       | 48        | 68     | 88      | 108      | 128     | 148 | 168 | 188  | 208  | 228  | 248 | TEC2       |
| 9        | 29       | 49        | 69     | 89      | 109      | 129     | 149 | 169 | 189  | 209  | 229  | 249 | Model500   |
| 10       | 30       | 50        | 70     | 90      | 110      | 130     | 150 | 170 | 190  | 210  | 230  | 250 |            |
| 11       | 31       | 51        | 71     | 91      | 111      | 131     | 151 | 171 | 191  | 211  | 231  | 251 | EHO        |
| 12       | 32       | 52        | 72     | 92      | 112      | 132     | 152 | 172 | 192  | 212  | 232  | 252 | Unknown    |
| 13       | 33       | 53        | 73     | 93      | 113      | 133     | 153 | 173 | 193  | 213  | 233  | 253 | No Reply   |
| 14       | 34       | 54        | 74     | 94      | 114      | 134     | 154 | 174 | 194  | 214  | 234  |     | но перју   |
| 15       | 35       | 55        | 75     | 95      | 115      | 135     | 155 | 175 | 195  | 215  | 235  |     |            |
| 16       | 36       | 56        | 76     | 96      | 116      | 136     | 156 | 176 | 196  | 216  | 236  |     |            |
| 17       | 37       | 57        | 77     | 97      | 117      | 137     | 157 | 177 | 197  | 217  | 237  |     |            |
| 18       | 38       | 58        | 78     | 98      | 118      | 138     | 158 | 178 | 198  | 218  | 238  |     |            |
| 19       | 39       | 59        | 79     | 99      | 119      | 139     | 159 | 179 | 199  | 219  | 239  |     |            |
| 20       | 40       | 60        | 80     | 100     | 120      | 140     | 160 | 180 | 200  | 220  | 240  |     | Help       |
|          |          |           |        |         |          |         |     |     |      |      |      |     | Close      |

3. Click stop and Close after the unit is able to identified by DCMlink<sup>™</sup> and at the protocol area, the unit tag will appear under comport.



4. Right click on the unit with "Detail Setup" and find the "Load configuration" button.

| Close Torque Limit         | 50                           | % (+   | ⇒ 50         | ) % 🗘                |
|----------------------------|------------------------------|--------|--------------|----------------------|
| Open Torque Limit          | 50                           | %      |              | ) % 🗘                |
| Enable RDM 1               | No                           | +      | → N          | •                    |
| Enable RDM 2               | No                           | +      | -> N         | •                    |
| Torque Retry               | No                           | +      | -> N         | •                    |
| Enable Low Battery Alarm   | No                           | +      | -> N         | •                    |
| Enable Battery Operation   | No                           | +      | -> N         | •                    |
| Enable Setpoint Tracking   | No                           | +      | -> N         | •                    |
| Valve Stall Delay Time     | 8 S                          | ec 🔶   | ⇒ 8          | Sec 🗘                |
|                            | r                            |        | $\frown$     | ì                    |
| Save Dataset Reset Dataset | Delete Dataset Copy From Tag | g Load | Configuratio | Export Configuration |

5. Load the configuration file from TEC2000 configuration file (\*.TEC or \*CFG)

|            | 135614B01.TEC |   | 4/4/2017 11:18 AM      | TEC Fi 🚽 |
|------------|---------------|---|------------------------|----------|
| •          |               |   |                        | F.       |
| File name: | 135614B01.TEC | • | TEC Docuements (*.TEC) | •        |
|            |               |   | Cfg Docuements (*.cfg) |          |
|            |               |   | TEC Docuements (*.TEC) |          |

6. After loading the configuration file, user will see the color changes through the load process.

| Control Discrete Inputs Re | lays Analog ESD/Inhibits | Speed | Network | : Cu | stom Characterization | Notes |
|----------------------------|--------------------------|-------|---------|------|-----------------------|-------|
| Parameter                  | Actuator                 |       |         |      | Dataset               |       |
| Control Mode               | Network                  |       | +       | -    | Analog                |       |
| Remote Control Signal      | Momentary                |       | -       | -    | Maintained            |       |
| Local Control Signal       | Momentary                |       | +       | >    | Momentary             |       |
| Seating                    | Position                 |       | -       | >    | Position              |       |
| Backseat                   | Position                 |       | -       | >    | Position              |       |
| LED Color                  | Open Red/Close Green     |       | -       | >    | Open Red/Close Green  |       |
| Close Torque Limit         | 50                       | %     | -       | >    | 50                    | %     |
| Open Torque Limit          | 50                       | %     | -       | >    | 50                    | %     |
| Enable RDM 1               | No                       |       | +       | >    | No                    |       |
| Enable RDM 2               | No                       |       | -       | >    | No                    |       |
| Torque Retry               | No                       |       | -       | >    | No                    |       |
| Enable Low Battery Alarm   | No                       |       | -       | >    | No                    |       |
| Enable Battery Operation   | No                       |       | -       | >    | No                    |       |
| Enable Setpoint Tracking   | No                       |       | -       | >    | No                    |       |
| Valve Stall Delay Time     | 8                        | Sec   | -       | >    | 0                     | Sec 🕻 |
|                            | r -                      | 1     |         |      | C                     |       |

Save Dataset Reset Dataset Delete Dataset Copy From Tag Load Configuration Export Configuration

Close Tag Help

a) Yellow Tag (the parameter needs to change after upload configuration file)



## b) Blue arrow

1) (Left arrow means write into configuration file, Right arrow means read from unit to overwrite the upload configuration.)

| Control Mode |    | Network Analog •  |
|--------------|----|---|
|              | 2) | In order to upload all of the parameter into actuator, user needs to click all "LEFT ARROW" at each lines and tags. |
| Control Mode |    | Analog  |

- 3) After all "LEFT ARROW" has been click, the tag color will change from "Yellow" to "Gray" which means the configuration has changed but hasn't save yet.
- 7. After all the changes made, exit out from the Setup.

| or Setup Calibratio    | n Diagnostics   | spec sneet    | 10015    | DCIVIIInk Setup | нер   |                                 |                |
|------------------------|---|---------------|----------|-----------------|---|---------------------------------|----------------|
|                        |   | ~ 🖍           |          |                 |   |                                 |                |
| «<br>rsion 1.2         | Dataset<br>New  | # Actuator Mc | ode      |                 | _   |                                 | <b>X</b> bm Ch |
| <b>AAAAAAAAA</b> AAAAA | Paramete<br>Discre<br>Function                        | Current Actua | itor Mod | le              | Actuator Mo                                     | <sup>de:</sup><br>Setup         | atase          |
| )M Slave)              | Setting <ul> <li>Discret</li> <li>Function</li> </ul> | New Actuator  | Mode     |                 | Enter Into Se<br>Enter Into Se<br>Exit from Set | tup Mode<br>tup Mode<br>up Mode | Active         |
|                        | Setting   | -             | -        | Active on Op    | oen Contact                                     | -                               | Active         |

 After all "Detial Setup" has been made, user needs change the "Factory Setting". It's at Tools/Factory/Factory Settings. \*\*note: if DCMlink<sup>™</sup> has no Emerson licensed, the factory setting will be disable till grant the licensed.

| Tools | DCMlink Setup   | Help   | _    |             |         |    |
|-------|-----------------|--------|------|-------------|---------|----|
| S     | cheduler        |        |      |             |         |    |
| В     | atch Runner     |        | ⊢    |             |         |    |
| A     | udit Log Viewer |        |      |             |         |    |
| E     | vent Log Viewer |        |      |             |         |    |
| D     | atabase         | •      | bits | Speed       | Network | Cu |
| N     | lemory Capture  |        |      |             |         |    |
| F     | actory          | •      |      | Factory Set | tings   |    |
| F     | actory          | •      |      | Factory Set | tings   | _  |
| e but | ton "Load       | config | gura | tion"       |         |    |
|       |                 |        | -    |             |         |    |

Load Configuration Export Configuration

a)

Read

Decommission

| Voltage<br>Frequency  |  |  |  |                                    |  |   |
|---|--|--|--|------------------------------------|--|---|
| Frequency   |  | 115 V  | +  | -                                  | 115 V  | • |
|   |  | 60 Hz  | +  | -                                  | 60 Hz  | • |
| Phase   |  | Single Phase   | -  | -                                  | Single Phase   | • |
| Auxiliary Contro  | ol Module  | None   | +  | -                                  | None   | • |
| Network Adapto  | or   | None   | <b>←</b>   | -                                  | MODBUS E>NET   | • |
| Starter   |  | Electro Mechanical   | 4  | -                                  | Electro Mechanical   | • |
| Torque Spring   |  | None   | 4  | -                                  | None   | • |
| Motor   |  | 000000000  | <b>(</b>   | -                                  | 9C1/21FC-C   |   |
| Horse Power   |  | 00000  | <b>←</b>   | >                                  | 1/4  |   |
| RPM   |  | 0000   | +  | >                                  | 1725   |   |
| Running Amps  |  | 0000   | <b>←</b>   | >                                  | 13.0   |   |
| Stalled Amps  |  | 0000   | <b>←</b>   | >                                  | 45.0   |   |
| Worm Gear   |  | Right Hand   | -  | -                                  | Right Hand   | • |
| Drive Sleeve  |  | Close CW   | -  | >                                  | Close CW   | • |
| Enable Auxiliary  | Relay Module                                     | No   | <b>(</b>   | >                                  | No   | • |
| Knobs Disabled  | On LDM   | No   | (  | -                                  | No   | • |
| Actuator Type   |  | Quarter-Turn   | -  | -                                  | Multi-Turn   | • |
|   | <u>-</u>   |  | CIVIC  | ~                                  | <b>N</b>   |   |
| 2   | 2) C   | Drive Sleeve (Close  | CW/Close C   | CW                                 | )  |   |
| ze Sleeve   | 2) C   | Drive Sleeve (Close  | CW/Close C   | CW                                 | Close CW   |   |
| ve Sleeve   | 2) D<br>3) V                                     | Drive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H   | CW/Close C   | CW<br>(Dand)                       | Close CW   |   |
| ve Sleeve<br>3<br>rm Gear                                       | 2) C<br>3) V                                     | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right Hand  | CW/Close C   | CW<br>and)                         | )<br>Close CW<br>Right Hand  |   |
| ze Sleeve<br>3<br>rm Gear<br>4                                  | 2) E<br>3) V<br>4) S                             | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand   | CW/Close C   | CW<br>and)<br>Cal N                | )<br>Close CW<br>Right Hand<br>Mech)                                       |   |
| 2<br>ve Sleeve<br>3<br>rm Gear<br>4<br>er                       | 2) E<br>3) V<br>4) S                             | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Starter Type(Solid S   | CW/Close C<br>mand/Left Ha<br>State/Electri  | CW<br>and)<br>Cal N                | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State                        |   |
| re Sleeve<br>3<br>rm Gear<br>4<br>rr                            | 2) E<br>3) V<br>4) S                             | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>tarter Type(Solid S<br>Solid State   | CW/Close C   | CCW<br>and)<br>Cal N               | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State                        |   |
| ze Sleeve<br>3<br>rm Gear<br>4<br>er<br>5                       | 2) E<br>3) V<br>4) S<br>5) P                     | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Starter Type(Solid State<br>Solid State<br>Phase(Single Phase  | CW/Close C<br>mand/Left Ha<br>State/Electri  | CCW<br>and)<br>cal M<br>(a)<br>(a) | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State                        |   |
| e Sleeve<br>3<br>m Gear<br>4<br>r<br>5<br>e                     | 2) C<br>3) V<br>4) S<br>5) P                     | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Starter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase  | CW/Close C<br>mand/Left Ha<br>State/Electri  | CCW<br>and)<br>cal N<br>e)         | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase        |   |
| e Sleeve<br>3<br>m Gear<br>4<br>r<br>5                          | 2) C<br>3) V<br>4) S<br>5) P<br>5) R             | Drive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>starter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase<br>Reverse Rotation(Y  | CW/Close C<br>mand/Left Ha<br>State/Electri<br>(Three phas<br>es/No)   | ccW<br>and)<br>cal M<br>e)         | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase        |   |
| s Sleeve<br>n Gear<br>5<br>se Rotation                          | 2) E<br>3) V<br>4) S<br>5) P<br>5) R             | Orive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>itarter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase<br>Reverse Rotation(Y<br>Yes   | CW/Close C<br>mand/Left Ha<br>State/Electri<br>(Three phas<br>(Three phas<br>(Es/No)   | ccW<br>and)<br>cal N<br>e)         | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase<br>Yes |   |
| rm Gear<br>4<br>er<br>5<br>ee<br>erse Rotation<br>7             | 2) E<br>3) V<br>4) S<br>5) P<br>5) R<br>7) F     | Drive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Starter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase<br>Reverse Rotation(Y<br>Yes<br>irmware CCM/LDM  | CW/Close C<br>mand/Left Ha<br>State/Electri<br>(Three phas<br>(Chree phas)<br>(Chree | ccW<br>and)<br>cal N<br>e)         | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase<br>Yes |   |
| ve Sleeve<br>m Gear<br>4<br>er<br>5<br>ie<br>erse Rotation<br>7 | 2) E<br>3) V<br>4) S<br>5) P<br>5) R<br>7) F     | Drive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Itarter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase<br>Reverse Rotation(Y<br>Yes<br>irmware CCM/LDN<br>A) CCM: 1.0.4                               | CW/Close C<br>mand/Left Ha<br>State/Electri<br>Three phas<br>es/No)<br>es/No)<br>M/RDM<br>4.   | CCW<br>and)<br>cal M<br>e)<br>•    | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase<br>Yes |   |
| re Sleeve 3<br>rm Gear 4<br>r 5<br>re 6<br>rrse Rotation 7      | 2) E<br>3) V<br>4) S<br>5) P<br>5) R<br>7) F     | Drive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Starter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase<br>Reverse Rotation(Y<br>Yes<br>Tirmware CCM/LDM<br>A) CCM: 1.0.4<br>Solid State<br>CCM: 1.0.4 | CW/Close C<br>mand/Left Ha<br>State/Electri<br>(Three phas<br>es/No)<br>(M/RDM<br>4.   | ccW<br>e)                          | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase<br>Yes |   |
| e Sleeve<br>m Gear<br>4<br>r<br>5<br>e<br>rse Rotation<br>7     | 2) E<br>3) V<br>4) S<br>5) P<br>5) R<br>7) F<br> | Drive Sleeve (Close<br>Close CW<br>Vorm Gear(Right H<br>Right Hand<br>Itarter Type(Solid S<br>Solid State<br>Phase(Single Phase<br>Single Phase<br>Reverse Rotation(Y<br>Yes<br>irmware CCM/LDN<br>A) CCM: 1.0.4<br>B) LDM: 1.0.4              | CW/Close C<br>mand/Left Ha<br>State/Electri<br>(Three phas<br>(Three phas<br>(M/RDM<br>4.<br>4.<br>4.  | CCW<br>and)<br>cal M<br>e)<br>•    | )<br>Close CW<br>Right Hand<br>Mech)<br>Solid State<br>Single Phase<br>Yes |   |

b) Click all blue "LEFT ARROW" to make the changes.



- 9. Completed configuration file migration from TEC2000 electronics to TEC2 electronics.
- 10. Export the final change of configuration file from TEC2 and send the copy of file back to Emerson as archive for future reference.
- 11. Commisson the unit.

## NOTE:

if user has difficulty to hav original TEC file, please consult Emerson team for supporting configuration file.

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